

Stability Estimates Of a Stochastic Inverse Source Problem For a Class of Elliptic Multipliers

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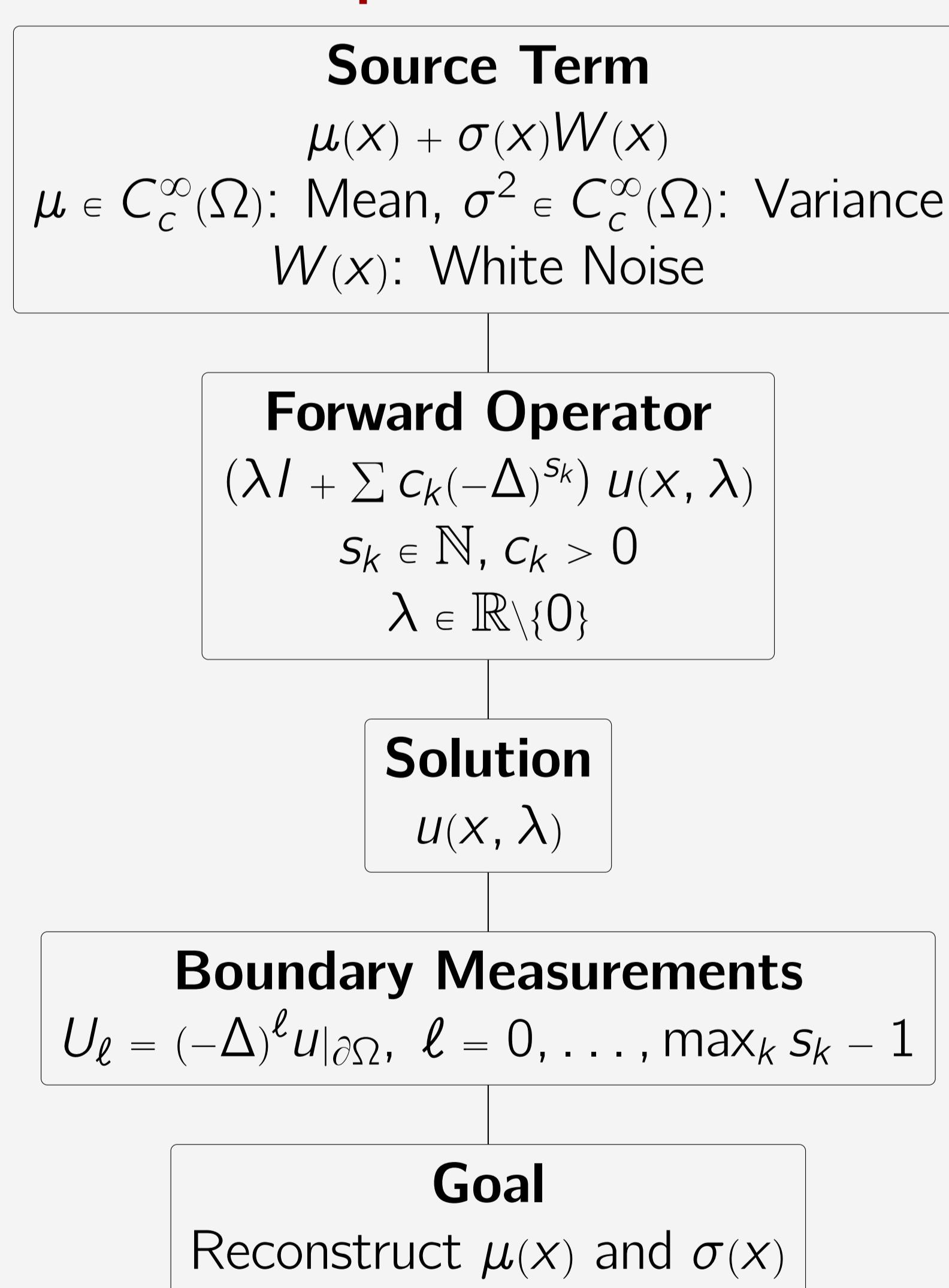
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1 Introduction

The challenge of recovering statistical information about an unknown, uncertain source from indirect and noisy observations is addressed within a mathematical modeling framework. The study focuses on an inverse source problem for differential operators involving high powers of the Laplacian. The source is modeled as a stochastic process, and explicit formulas are derived to reconstruct its mean and variance. Stability to noise is established, and the method is validated numerically.

2 Problem Setup



3 Remark

Under the chosen boundary conditions, the solution exists, is unique, and admits the representation

$$u(x, \lambda) = \int_{\Omega} \Phi(x - y, \lambda) \mu(y) dy + \int_{\Omega} \Phi(x - y, \lambda) \sigma(y) dW_y,$$

where $\Phi(x - y, \lambda)$ is the Green's function (fundamental solution) of the operator. The first term is deterministic, while the second is a stochastic integral driven

4 Method and Reconstruction Formulas

For $x \in \Omega \subset \mathbb{R}^n$ and $j = 1 \dots \infty$, $\tilde{s} = \max_k s_k$ consider

$$(\lambda_j I + \sum_{k=1}^N c_k (-\Delta)^{s_k}) u_j(x, \lambda_j) = \mu(x) + \sigma(x) W(x),$$

with our measurement when $x \in \partial\Omega$

$$(-\Delta)^\ell u_j(x, \lambda_j) = U_{j,\ell}(x, \lambda_j) \text{ for all } \ell = 0, \dots, \tilde{s} - 1$$

1. Multiply the main equation by ϕ_j and integrate over $\Omega \subset \mathbb{R}^n$ where $\{\phi_j\}_{j=1}^\infty$ are the eigenfunctions of $-\Delta$

2. Use

$$\begin{aligned} \langle (-\Delta)^{s_k} u, \phi_j \rangle_{L^2(\Omega)} &= \sum_{d=1}^{s_k} \left[\langle (-\Delta)^{s_k-d} u, \partial_\nu (-\Delta)^{d-1} \phi_j \rangle_{L^2(\partial\Omega)} \right. \\ &\quad \left. - \langle (-\Delta)^{d-1} \phi_j, \partial_\nu (-\Delta)^{s_k-d} u \rangle_{L^2(\partial\Omega)} \right] + \langle u, (-\Delta)^{s_k} \phi_j \rangle_{L^2(\Omega)} \end{aligned}$$

We get:

$$\langle f, \phi_j \rangle_{L^2(\Omega)} = \sum_{k=1}^N c_k \sum_{d=1}^{s_k} \kappa_j^{d-1} \langle U_{j,s_k-d}, \partial_\nu \phi_j \rangle_{L^2(\partial\Omega)}$$

Expression of $f(x)$

$$f(x) = \sum_{j=1}^{\infty} \left[\sum_{k=1}^N \sum_{d=1}^{s_k} c_k \kappa_j^{d-1} \langle U_{j,s_k-d}, \partial_\nu \phi_j \rangle_{L^2(\partial\Omega)} \right] \phi_j(x)$$

Expression of $\mu(x)$

$$\mu(x) = \sum_{j=1}^{\infty} \left[\sum_{k=1}^N \sum_{d=1}^{s_k} c_k \kappa_j^{d-1} \langle \mathbb{E}(U_{j,s_k-d}), \partial_\nu \phi_j \rangle_{L^2(\partial\Omega)} \right] \phi_j(x)$$

Expression of $\sigma^2(x)$

$$\begin{aligned} \sigma^2(x) &= \sum_{j=1}^{\infty} \left[\sum_{k=1}^N \sum_{d=1}^{s_k} c_k^2 (\kappa_j^{d-1})^2 \operatorname{Var}(\langle U_{j,s_k-d}, \partial_\nu \phi_j \rangle) \right. \\ &\quad \left. + \sum_{(k,d) \neq (k',d')} c_k c_{k'} \kappa_j^{d-1} \kappa_{j'}^{d'-1} \operatorname{Cov}(\langle U_{j,s_k-d}, \partial_\nu \phi_j \rangle, \langle U_{j',s_{k'}-d'}, \partial_\nu \phi_{j'} \rangle) \right] \phi_j^2(x) \end{aligned}$$

5 Stability Estimates

Assume

$$\sum_{j=1}^{\infty} [\mathbb{E}(U_{j,s_k-d}^{(1)} - U_{j,s_k-d}^{(2)})]^2 < S < \infty$$

and $r = 2s_k + \frac{n}{2} + \epsilon - 1$

$$\|\mu_1 - \mu_2\|_{L^2(\Omega)}^2 \leq \sum_{j=1}^{\infty} \sum_{k=1}^N \sum_{d=1}^{s_k} \tilde{C} \kappa_j^{-\frac{n}{2}-\epsilon} \cdot \mathbb{E}(U_{j,s_k-d}^{(1)} - U_{j,s_k-d}^{(2)})^2_{H^r(\partial\Omega)}$$

and for $\tilde{s} < \frac{n}{4} + 1$ where $\tilde{s} = \max_k s_k$

$$\|\sigma_1^2(x) - \sigma_2^2(x)\|_{L^2(\Omega)}^2 \leq D^2 < \infty$$

where $D = \varrho_2 \cdot \zeta(\frac{4-4\tilde{s}}{n})$ and ϱ_2 is a constant and $\zeta(\alpha)$ is the Riemann zeta function.

6 Numerical Example (1D Case)

We solve a numerical example in one dimension where the equation takes the form:

$$(\lambda_j I - \Delta)u = f(x), \quad \text{in } (0, 1) \subset \mathbb{R},$$

with eigenvalues $\lambda_j = -j^2\pi^2$ and the following boundary conditions:

$$\begin{cases} -u'(0) = i\sqrt{|\lambda|} u(0), \\ u'(1) = i\sqrt{|\lambda|} u(1). \end{cases}$$

We get

